





The UR60 device is a remote numerical control designed to be placed on a DIN bar. The control include serial and Ethernet communications (RS232 and RS422/485), CAN bus field, control of up to 6 analog axes, 8 digital axis on Mechatrolink bus, 4 analog inputs and 2 analog outputs auxiliary, 16 Internal Inputs and 16 internal Outputs, I/O expansion on BLT or CAN. The CPU used is a FREESCALE MCF5235 ColdFire Processor at 150Mhz that is compatible with the others TESE products and permits future development with the higher-performance ColdFire family.



CHARACTERISTICS	DESCRIPTION	NOTES
	GENERAL	
Dimensions	220 mm x 150mm x50mm	-
Installation	On DIN bar	-
Weight (plus DIN bar hook)	approx. 700 g	-
Operating environment	Industrial	-
Protection class	IP20	-
Operating temperature	From 0° to 50°C	-
Operating humidity (without condensate)	≤75%	-





CHARACTERISTICS	DESCRIPTION	NOTES
CHARACTERISTICS	ELECTRICAL	NOTES
	DC 24V ±10%	-
Supply voltage	AC 24V ±10%	
Power supply	To be defined	-
Buffer battery	CR2032 Battery	-
Encoder power supply	+5V / +12V (Line Driver / Open Collector)	- Internal power supply
Analog outputs	±10V 16 bit	-
	CONNECTIONS	
Serial	1 RS232C line	- Su DB9
Ethernet	1 Ethernet connection to user interface PC	- RJ45 – Auto sense
Field bus		- DSP-DS301/401 communication protocol
	2 CANOpen line	- on 5-pin connector
USB connector	F11	- Rotoswitch to the address selection - Mass Storage
Mechatrolink	For local upgrade and downgrade 1 Mechatrolink connector	- Mass Storage - Omron / Yaskawa proprietary field-bus
Local bus	1 line for local control of 80 inputs/outputs	- Official / Taskawa proprietary field-bus
Local bus	6 encoder inputs +5/+12V Line driver - Open	-
Encoder inputs	collector	
In-flight position connection inputs	6 inputs for PNP position connection	
Reference switch inputs	6 digital inputs as reference switch	On axis connector
Analog Outputs	2 analog outputs ±10V 16 bit	- on one DB9 connector
	4 Analog Inputs	
Analog Inputs	1 potientometer power supply +10V	- on DB9
Internal PLC Inputs and Outputs	16 Inputs + 16 Outputs	
	CPU	
Microprocessor	FREESCALE MCF5235 @150MHZ	
	Flash 2MB, parallel 16bit	
Working memory	RAM 1MB 16bit	- Battery Buffered
	RAM 2MB fast static	
	AXIS	
Encoder interface Encoder count	Line driver, Open collector 5/12V 500 KHz with multiplication by 4	- Configurable with jumpers
Encoder count	3/6 msec with PLC scanning time	-
Real Time	programmable from the application	-
Analog reference	±10 Volt	- 16bit resolution with mark
Limit switch inputs	1 per axis	-
In-flight position connection inputs	1 per axis	-
	- Axis disable in case of error	
Axis Monitoring	- Software limit control	
	- Tracking error control	
	- Motion control on individual axis	- Based on fully-developed PID
Drive Control	- Possibility of in-flight position connection	-
	for high-precision mode	
	- Automatic axis offset connection	-
	- Positioning with trajectory control - Linear and circular interpolation	Possibility to define the working plane in the
	- Automatic interpolation speed adjustment	space
Axis performance	on the connectors and direction change	-
Table performance	- S-ramp	
	- Interpolation with 2 C-axes for tangent	
	cutting	-
	- Electrical axis (Gantry)	-
	SOFTWARE	
Development and analysis environment	SyncroView32	- Automatic monitoring of the last 6 sec.
		- For the axes, dedicated instructions for
1	DIC II b · · · / I · · · · · · · · · · · ·	punching and form-pressing functions
Languages available	- PLC on IL basis (Instruction List) - SBL	- Possibility of defining parallel processes - Set of commands for motion control (axes)
	- SDL	with parallel processes and interaction with and
		by the PLC
	EXPANSIONS	oj die i De
	Digital inputs, Digital outputs, Relay outputs,	
Tecnos Module on BLT	D/A converter module, A/D converter	Maximun number of I/O: 80IN+80OUT
	module,	